## Low-Speed Rotary Actuator

## Possible to transfer a workpiece at low-speed.



Stable motion at $5 \mathrm{~s} / 90^{\circ}$.
Smooth motion without stick-slip phenomenon.


Measurement conditions: Fluid: Air.
Mounting orientation: Horizonal without load.
Operating pressure: 0.5 MPa .
Pneumatic circuit: Meter-out circuit.
Ambient temperature: Room temperature
Dimensions compatible with the CRQ2 and MSQ series


## Series CRQ2X/MSQX Model Selection

* The selection procedure of a low-speed rotary is the same as for an ordinary rotary. If the rotation time exceeds 2s per $90^{\circ}$, however, the necessary torque and the kinetic energy are calculated with rotation time of 2 s per $90^{\circ}$.


## Selection Procedure <br> Remarks <br> Selection Example

## Operating conditions

Operating conditions are as follows:

- Provisionally selected model
- Operating pressure: MPa
- Mounting position
- Load type

Static load: N.m
Resistance load: N.m
Inertial load: N•m

- Load dimension: m
- Load mass: kg
- Rotation time: s
- Rotation angle: rad
- See P. 3 for load type.
- The unit of the rotation angle is Radians.
$180^{\circ}=\pi \mathrm{rad}$
$90^{\circ}=\pi / 2 \mathrm{rad}$


## Calculation of moment of inertia

Calculate the moment of inertia of the load.
$\Rightarrow$ P. 2

- If the moment of inertia of the load is made up of multiple components, calculate the moment of inertia of each component and add them together.

$$
\begin{aligned}
& \text { Load } 1 \text { moment of inertia: } I_{1} \\
& \qquad I_{1}=0.4 \times \frac{0.15^{2}+0.05^{2}}{12}+0.4 \times 0.05^{2}=0.001833
\end{aligned}
$$

$$
\text { Load } 2 \text { moment of inertia: } \mathbf{I}_{2}
$$

$$
I_{2}=0.2 \times \frac{0.025^{2}}{2}+0.2 \times 0.1^{2}=0.002063
$$

Total moment of inertia: I
$\mathbf{I}=\mathbf{I}_{1}+\mathbf{I}_{\mathbf{2}}=\mathbf{0 . 0 0 3 8 9 6}\left[\mathrm{kg} \cdot \mathrm{m}^{2}\right]$

## Calculation of necessary torque

Calculate necessary torque corres-
ponding to the load type, and ensure
it is within effective torque range.

- Static load (Ts)

Necessary torque T = Ts

- Resistance load (Tf)

Necessary torque T = Tf x (3 to 5)

- Inertial load (Ta)

Necessary torque $T=T a \times 10$
$\Rightarrow$ P. 3

## Checking rotation time

Confirm that it is within the adjustable range of rotation time.
$\Rightarrow$ P. 4

- When calculating the inertial load, if the rotation time exceeds 2 s per $90^{\circ}$, inertial load is calculated with rotation time of 2 s per $90^{\circ}$.
- Even for resistance load, when the load is rotated, necessary torque calculated from inertial load shall be added.

Necessary torque
$\mathrm{T}=\mathrm{Tf} \mathbf{x}$ (3 to 5) $+\mathrm{Ta} \times 10$

## Inertial load: Ta

$\mathrm{Ta}=\mathbf{I} \cdot \dot{\omega}$
$\dot{\omega}=\frac{2 \theta}{\mathbf{t}^{2}}\left[\mathrm{rad} / \mathrm{s}^{2}\right]$
Necessary torque: $\mathbf{T}$
$\mathrm{T}=\mathrm{Ta} \times 10$
$=0.003896 \times \frac{2 \times \pi}{4^{2}} \times 10=0.015[\mathrm{~N} \cdot \mathrm{~m}]$
( $t$ is calculated with 2 s per $90^{\circ}$.)
$0.109 \mathrm{~N} \cdot \mathrm{~m}$ < Effective torque OK

## Calculation of kinetic energy

Confirm that the load's kinetic energy
is within the allowable value.
Confirm it with the graph of the moment of inertia and the rotation time.

$$
\Rightarrow \text { P. } 4
$$

- Converted to the time per $90^{\circ}$ for comparison. (For example, $6 \mathbf{s} / 180^{\circ}$ is converted to $3 \mathrm{~s} / 90^{\circ}$.)

$$
\begin{aligned}
& 1.0 \leq t \leq 5 \\
& t=3 \mathrm{~s} / 90^{\circ} \mathrm{OK}
\end{aligned}
$$

- If the rotation time exceeds 2 s per $90^{\circ}$, kinetic energy is calculated with rotation time of 2 s per $90^{\circ}$.
- If the allowable value is exceeded, an external cushioning mechanism, such as an absorber, needs to be installed.
$E=\frac{1}{2} \cdot I \cdot \omega^{2}$
$\omega=\frac{2 \cdot \theta}{t}$
Kinetic energy
$E=\frac{1}{2} \times 0.003896 \times\left(\frac{2 \times \pi}{4}\right)^{2}=0.0048$ [J]
( t is calculated with 2 s per $90^{\circ}$.)
0.0048 [J] < Allowable energy OK


## Checking allowable load

Check if the load applied to the product is within the allowable range.
$\Rightarrow$ P. 5

- If the allowable value is exceeded, an external bearing needs to be installed.

$$
\begin{aligned}
\mathrm{M} & =0.4 \times 9.8 \times 0.05+0.2 \times 9.8 \times 0.1 \\
& =0.392[\mathrm{~N} \cdot \mathrm{~m}]
\end{aligned}
$$

0.392 [N•m] < Allowable moment load OK

## Calculation of air consumption and necessary air quantity

Calculate air consumption and necessary air quantity as required. $\Rightarrow$ P. 6

## Equation Table of Moment of Inertia (Calculation of moment of inertia I)

1. Thin shaft

Position of rotational axis:
Perpendicular to the shaft through the centre of gravity

2. Thin rectangular plate

Position of rotational axis:
Parallel to side $b$ through the centre of gravity

3. Thin rectangular plate (Including rectangular parallelepiped)
Position of rotational axis:
Perpendicular to the plate through the centre of gravity


$$
\mathrm{I}=\mathbf{m} \cdot \frac{\mathbf{a}^{2}+\mathbf{b}^{2}}{12}
$$

## 4. Round plate

Position of rotational axis:
Passing through the centre axis

6. Thin round plate

Position of rotational axis:
Passing through the diameter


$$
I=m \cdot \frac{r^{2}}{4}
$$

7. Cylindrical

Position of rotational axis:
Passing through the diameter and the centre of gravity


$$
I=\mathbf{m} \cdot \frac{3 \mathbf{r}^{2}+\mathbf{a}^{2}}{12}
$$

8. Rotational axis and the centre of the load are not concentric.

$\mathbf{I}=\mathbf{K}+\mathbf{m} \cdot \mathbf{L}^{2}$
$\mathbf{K}$ : The moment of inertia around the centre of gravity of the load
In case of 4. Round plate $\mathbf{K}=\mathbf{m} \cdot \frac{\mathbf{r}^{2}}{2}$

## 9. Gear transmission


5. Solid sphere

Position of rotational axis:
Passing through the diameter


$$
\mathrm{I}=\mathrm{m} \cdot \frac{2 \mathrm{r}^{2}}{5}
$$

## Model Selection

## Load Type

Necessary torque calculation method depends on the load type. Refer to the table below.

| Load type |  |  |
| :---: | :---: | :---: |
| Static load: Ts | Resistance load: Tf | Inertial load: Ta |
| Only pressing force is necessary (e.g. for clamping). | Weight or friction force is applied to rotating direction. | Rotate the load with inertia. |
|  | Gravity is applied. <br> Friction force is applied. | Centre of rotation and centre of gravity of the load are concentric. <br> Rotation shaft is vertical (up and down) |
| $\mathbf{T s}=\mathbf{F} \cdot \ell$ <br> Ts: Static load ( $\mathrm{N} \cdot \mathrm{m}$ ) <br> F: Clamping force (N) <br> $l$ : Distance from the rotation centre to the clamping position (m) | Gravity is applied in rotating direction. $\mathbf{T f}=\mathbf{m} \cdot \mathbf{g} \cdot \ell$ <br> Friction force is applied in rotating direction. $\mathbf{T f}=\mu \cdot \mathbf{m} \cdot \mathbf{g} \cdot \ell$ <br> Tf : Resistance load ( $\mathrm{N} \cdot \mathrm{m}$ ) <br> m : Load mass (kg) <br> g : Gravitational acceleration $9.8\left(\mathrm{~m} / \mathrm{s}^{2}\right)$ <br> $l$ : Distance from the rotation centre to the point of application of the weight or friction force ( m ) <br> $\mu$ : Friction coefficient | $\begin{aligned} & \mathbf{T a}=\mathrm{I} \cdot \omega=\mathrm{I} \cdot \frac{2 \theta}{\mathbf{t}^{2}} \\ & \mathrm{Ta}: \text { Inertial load }(\mathrm{N} \cdot \mathrm{~m}) \\ & \mathrm{I}: \text { Moment of inertia }\left(\mathrm{kg} \cdot \mathrm{~m}^{2}\right) \\ & \omega: \text { Angular acceleration }\left(\mathrm{rad} / \mathrm{s}^{2}\right) \\ & \theta: \text { Rotation angle }(\mathrm{rad}) \\ & \mathbf{t}: \text { Rotation time }(\mathrm{s}) \end{aligned}$ <br> For low speed rotary, if the rotation time exceeds $2 s$ per $90^{\circ}$, inertial load is calculated with rotation time of 2 s per $90^{\circ}$. |
| Necessary torque: $\mathbf{T}=\mathbf{T s}$ | Necessary torque: $\mathbf{T}=\mathbf{T f} \times$ (3 to 5) ${ }^{\text {Note }}$ ) | Necessary torque: $\mathbf{T}=\mathbf{T a} \times 10^{\text {Note) }}$ |
| - Resistance load: Gravity or friction force is ap <br> Ex. 1) Rotation shaft is horizontal (lateral), <br> Ex. 2) Load moves by sliding on the floor <br> Note 1) The total of resistance load and inertia Note 2) To adjust the speed, margin is necess <br> - Not resistance load: Nor weight nor friction fo <br> Ex. 1) Rotation shaft is vertical (up and down) <br> Ex. 2) Rotation shaft is horizontal (lateral), | rotating direction. rotation centre and the centre of gravity of the load <br> the necessary torque. $\mathbf{T}=\mathbf{T f} \times(3$ to 5$)+\mathbf{T a} \times 10$ Tf and Ta . <br> e applied in rotating direction. <br> ation centre and the centre of gravity of the load are | ot concentric. <br> oncentric. |

Note) Necessary torque is inertial load only. $\mathbf{T}=\mathbf{T a} \times 10$

## Effective Torque

| Unit: N•m |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Model | Size | Operating pressure (MPa) |  |  |  |  |  |  |  |  |  |  |
|  |  | 0.1 | 0.15 | 0.2 | 0.3 | 0.4 | 0.5 | 0.6 | 0.7 | 0.8 | 0.9 | 1.0 |
| CRQ2X | 10 | - | 0.09 | 0.12 | 0.18 | 0.24 | 0.30 | 0.36 | 0.42 | - | - | - |
|  | 15 | - | 0.22 | 0.30 | 0.45 | 0.60 | 0.75 | 0.90 | 1.04 | - | - | - |
|  | 20 | 0.37 | 0.55 | 0.73 | 1.10 | 1.47 | 1.84 | 2.20 | 2.57 | 2.93 | 3.29 | 3.66 |
|  | 30 | 0.62 | 0.94 | 1.25 | 1.87 | 2.49 | 3.11 | 3.74 | 4.37 | 4.99 | 5.60 | 6.24 |
|  | 40 | 1.06 | 1.59 | 2.11 | 3.18 | 4.24 | 5.30 | 6.36 | 7.43 | 8.48 | 9.54 | 10.6 |
| MSQX | 10 | 0.18 | - | 0.36 | 0.53 | 0.71 | 0.89 | 1.07 | 1.25 | 1.42 | 1.60 | 1.78 |
|  | 20 | 0.37 | - | 0.73 | 1.10 | 1.47 | 1.84 | 2.20 | 2.57 | 2.93 | 3.29 | 3.66 |
|  | 30 | 0.55 | - | 1.09 | 1.64 | 2.18 | 2.73 | 3.19 | 3.82 | 4.37 | 4.91 | 5.45 |
|  | 50 | 0.93 | - | 1.85 | 2.78 | 3.71 | 4.64 | 5.57 | 6.50 | 7.43 | 8.35 | 9.28 |




Note 1) Operating torque values in above table are representative values, not guaranteed. Make use of the values as a reference when ordering.
Note 2) Except for cases when an external stopper is used, the holding torque at the operation end is half of the table value.

## Kinetic Energy / Rotating Time

In a rotational movement, the kinetic energy of a load may damage the internal parts, even if the required torque for a load is small. Consider the moment of inertia and rotation time before selecting a model.
(For model selection, refer to the moment of inertia and rotation time graph as shown on the table below.)

## Allowable kinetic energy and rotation time adjustment range:

Set the rotation time, within stable operational guidelines, using the adjustment range specification table as detailed below.
If operating at low-speeds the rotation time adjustment range is exceeded, use caution as it may result in sticking or malfunction.

| Model | Size | Allowable kinetic energy (J) | Stable operational rotation time adjustment range (s/90 ${ }^{\circ}$ ) |
| :---: | :---: | :---: | :---: |
| CRQ2X | 10 | 0.00025 | 0.7 to 5 |
|  | 15 | 0.00039 |  |
|  | 20 | 0.025 | 1 to 5 |
|  | 30 | 0.048 |  |
|  | 40 | 0.081 |  |
| MSQX | 10 | 0.007 |  |
|  | 20 | 0.025 |  |
|  | 30 | 0.048 |  |
|  | 50 | 0.081 |  |

Model Selection
Select a model based on the moment of inertia and rotation time as shown on graph below.

CRQ2X


MSQX


[^0]
## Model Selection

## Allowable Load

## CRQ2X

A load up to the allowable radial/thrust load can be applied. However, applications which apply a load directly to the shaft should be avoided whenever possible. In order to further improve the operating conditions, a method such as that shown in the drawing on the right side is recommended so that a direct load is not applied to the shaft.


## MSQX

Do not allow the load and moment applied to the table to exceed the allowable values shown in the table below.
(Operation beyond the allowable values can cause adverse effects on service life, such as play in the table and loss of accuracy.)

| Size |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Allowable radial load ( N ) | Allowable thrust load (N) |  | Allowable moment ( $\mathrm{N} \cdot \mathrm{m}$ ) |
|  |  | (a) | (b) |  |
| 10 | 78 | 74 | 78 | 2.4 |
| 20 | 147 | 137 | 137 | 4.0 |
| 30 | 196 | 197 | 363 | 5.3 |
| 50 | 314 | 296 | 451 | 9.7 |

## Rotary Actuator Technical Data Air Consumption

Air consumption is the volume of air which is expended by the rotary actuator's reciprocal operation inside the actuator and in the piping between the actuator and the switching valve, etc. This is necessary for selection of a compressor and for calculation of its running cost.
Note) The air consumption (QcR) required for one reciprocation of the rotary actuator alone is shown in the table below, and can be used to simplify the calculation.

Formulas
$Q_{C R}=2 \mathrm{~V} \times\left(\frac{P+0.1}{0.1}\right) \times 10^{-3}$
$Q_{C P}=2 \times \mathrm{a} \times e \times\left(\frac{P}{0.1}\right) \times 10^{-6}$
$Q_{C}=Q_{C R}+Q_{C P}$
$Q_{C R}=$ Air consumption of rotary actuator
QcP = Air consumption of tubing or piping
$\mathbf{V}=$ Internal volume of rotary actuator
$\mathbf{P}=$ Operating pressure
$\ell=$ Length of piping
$\mathbf{a}=$ Internal cross section of piping
Qc = Air consumption required for one reciprocation of rotary actuator

When selecting a compressor, it is necessary to choose one which has sufficient reserve for the total air consumption of pneumatic actuators downstream. This is affected by factors such as leakage in piping, consumption by drain valves and pilot valves, etc., and reduction of air volume due to drops in temperature.

## Formulas

Reserve factor: 1.5 or greater

Internal Cross Section of Tubing and Steel Piping

| Nominal size | O.D. (mm) | I.D. (mm) | Internal cross section <br> $\mathbf{a ( m ^ { 2 } )}$ |
| :---: | :---: | :---: | :---: |
| T $\square \mathbf{0 4 2 5}$ | 4 | 2.5 | 4.9 |
| T $\square 0604$ | 6 | 4 | 12.6 |
| TU0805 | 8 | 5 | 19.6 |
| T $\square \mathbf{0 8 0 6}$ | 8 | 6 | 28.3 |
| 1/8B | - | 6.5 | 33.2 |
| T $\square \mathbf{1 0 7 5}$ | 10 | 7.5 | 44.2 |
| TU1208 | 12 | 8 | 50.3 |
| T $\square \mathbf{1 2 0 9}$ | 12 | 9 | 63.6 |
| $\mathbf{1 / 4 B}$ | - | 9.2 | 66.5 |
| TS1612 | 16 | 12 | 113 |
| 3/8B | - | 12.7 | 127 |
| T $\square \mathbf{1 6 1 3}$ | 16 | 13 | 133 |
| $\mathbf{1 / 2 B}$ | - | 16.1 | 204 |
| 3/4B | - | 21.6 | 366 |
| $\mathbf{1 B}$ | - | 27.6 | 598 |

## Qc2 $=$ Qc $\times \mathrm{n} \times$ Number of actuators $\times$ Reserve factor

$\mathbf{Q c}_{2}=$ Compressor discharge flow rate
[ $/$ /min (ANR)]
$\mathbf{n}=$ Actuator reciprocations per minute
[/min

Air Consumption
$[\ell($ ANR $)]$
$[\ell($ ANR $)]$
$\left[\mathrm{cm}^{3}\right]$
$[\mathrm{MPa}]$
$[\mathrm{mm}]$
$\left[\mathrm{mm}^{2}\right]$
$[\ell($ ANR $)]$
,
[MPa]
[mm]
[ $\mathrm{mm}^{2}$ ]
[ (ANR)]

| Model | Size | Rotation angle <br> ( ${ }^{\circ}$ ) | Internal volume$\mathrm{V}\left(\mathrm{~cm}^{3}\right)$ | Operating pressure ( MPa ) |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | 0.1 | 0.15 | 0.2 | 0.3 | 0.4 | 0.5 | 0.6 | 0.7 | 0.8 | 0.9 | 1.0 |
| CRQ2X | 10 | 90 | 1.2 | - | 0.006 | 0.007 | 0.009 | 0.012 | 0.014 | 0.016 | 0.018 | - | - | - |
|  |  | 180 | 2.2 | - | 0.011 | 0.013 | 0.018 | 0.022 | 0.026 | 0.031 | 0.035 | - | - | - |
|  | 15 | 90 | 2.9 | - | 0.015 | 0.017 | 0.023 | 0.029 | 0.035 | 0.041 | 0.046 | - | - | - |
|  |  | 180 | 5.5 | - | 0.028 | 0.033 | 0.044 | 0.055 | 0.066 | 0.077 | 0.088 | - | - | - |
|  | 20 | 90 | 7.1 | 0.028 | 0.036 | 0.043 | 0.057 | 0.071 | 0.085 | 0.099 | 0.114 | 0.128 | 0.142 | 0.156 |
|  |  | 180 | 13.5 | 0.054 | 0.068 | 0.081 | 0.108 | 0.135 | 0.162 | 0.189 | 0.216 | 0.243 | 0.270 | 0.297 |
|  | 30 | 90 | 12.1 | 0.048 | 0.060 | 0.073 | 0.097 | 0.121 | 0.145 | 0.169 | 0.193 | 0.218 | 0.242 | 0.266 |
|  |  | 180 | 23.0 | 0.092 | 0.115 | 0.138 | 0.184 | 0.230 | 0.276 | 0.322 | 0.368 | 0.413 | 0.459 | 0.505 |
|  | 40 | 90 | 20.6 | 0.082 | 0.103 | 0.123 | 0.164 | 0.206 | 0.247 | 0.288 | 0.329 | 0.370 | 0.411 | 0.452 |
|  |  | 180 | 39.1 | 0.156 | 0.195 | 0.234 | 0.313 | 0.391 | 0.469 | 0.547 | 0.625 | 0.703 | 0.781 | 0.859 |
| MSQX | 10 | 190 | 6.6 | 0.026 | 0.033 | 0.040 | 0.053 | 0.066 | 0.079 | 0.092 | 0.106 | 0.119 | 0.132 | 0.145 |
|  | 20 |  | 13.5 | 0.054 | 0.068 | 0.081 | 0.108 | 0.135 | 0.162 | 0.189 | 0.216 | 0.243 | 0.270 | 0.297 |
|  | 30 |  | 20.1 | 0.080 | 0.101 | 0.121 | 0.161 | 0.201 | 0.241 | 0.281 | 0.322 | 0.362 | 0.402 | 0.442 |
|  | 50 |  | 34.1 | 0.136 | 0.171 | 0.205 | 0.273 | 0.341 | 0.409 | 0.477 | 0.546 | 0.614 | 0.682 | 0.750 |

# Low-Speed Compact Rotary Actuator Rack \& Pinion Type Series CRQ2X Size: 10, 15, 20, 30, 40 

How to Order


Applicable Auto Switches / Refer to pages 24 through to 27 for further information about auto switches.

| $\stackrel{\otimes}{\stackrel{\circ}{\gtrless}}$ | Special function | Electrical entry | $\begin{array}{\|l} \hline \stackrel{\rightharpoonup}{0} \\ \stackrel{\rightharpoonup}{\tilde{0}} \\ \text { 음 } \\ \underline{\underline{O}} \end{array}$ | Wiring (Output) | Load voltage |  |  | Auto switch model |  | Lead wire length (m) Note 1) |  |  |  | Applicable load |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | DC |  | AC |  |  | $\begin{array}{r} 0.5 \\ \text { (Nil) } \\ \hline \end{array}$ | $\begin{gathered} 1 \\ (\mathrm{M}) \end{gathered}$ | $\begin{gathered} 3 \\ (\mathrm{~L}) \\ \hline \end{gathered}$ | $\begin{gathered} 5 \\ (\mathrm{Z}) \end{gathered}$ |  |  |
|  |  |  |  |  |  |  | Perpendicular | In-line |  |  |  |  |  |  |
|  |  | Grommet | Yes | 3-wire (NPN) | $5 \mathrm{~V}, 12 \mathrm{~V}$ |  |  | - | M9NV | M9N | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | IC | Relay, PLC |
|  | - |  |  | 3-wire (PNP) |  |  | M9PV |  | M9P | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | circuit |  |
|  |  |  |  | 2-wire | 24 V | 12 V | M9BV |  | M9B | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | - |  |
|  | Diagnostic indication (2-colour) |  |  | 3-wire (NPN) |  | $5 \mathrm{~V}, 12 \mathrm{~V}$ | M9NWV |  | M9NW | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | IC |  |
|  |  |  |  | 3-wire (PNP) |  |  | M9PWV |  | M9PW | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | circuit |  |
|  |  |  |  | 2-wire |  | 12 V | M9BWV |  | M9BW | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | - |  |
|  | Water resistant (2-colour) |  |  | 3-wire (NPN) |  | $5 \mathrm{~V}, 12 \mathrm{~V}$ | M9NAV |  | M9NA | $\bigcirc$ | $\bigcirc$ | - | $\bigcirc$ | IC circuit |  |
|  |  |  |  | 3-wire (PNP) |  |  | M9PAV |  | M9PA | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |  |  |
|  |  |  |  | 2-wire |  | 12 V | M9BAV |  | M9BA | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - |  |
|  | - | Grommet | No | 2-wire | 24 V | 12 V | 100 V or less | A90V | A90 | $\bigcirc$ | - | $\bigcirc$ | - | IC circuit | Relay, PLC |  |
|  |  |  | Yes | 3-wire (NPN equiv.) | - | 5 V | - | A96V | A96 | $\bigcirc$ | - | $\bigcirc$ | - |  | - |  |
|  |  |  |  | 2-wire | 24 V | 12 V | 100 V | A93V | A93 | $\bigcirc$ | - | - | - | - | Relay, PLC |  |

Note 1)Lead wire length symbols: $0.5 \mathrm{~m} \cdots \ldots$. (Example) M9NW

| $1 \mathrm{~m} \ldots \ldots . \mathrm{M}$ | M9NWM |
| :--- | :--- |
| $3 \mathrm{~m} \ldots \ldots . \mathrm{L}$ | M9NWL |

Note 2) Ithough it is possible to mount water resistant type auto switches, note that the rotary actuator itself is not water resistant.

- Auto switches marked with " $\bigcirc$ " are manufactured upon a receipt of order
- For details about auto switches with pre-wired connector, refer to "SMC Best Pneumatics 2004" Vol. 11 catalogue.
- Auto switches are shipped together, but not assembled.


## Specifications



| Size | 10 | 15 | 20 | 30 | 40 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Fluid | Air (Non-lube) |  |  |  |  |
| Max. operating pressure | 0.7 MPa |  | 1 MPa |  |  |
| Min. operating pressure | 0.15 MPa |  | 0.1 MPa |  |  |
| Ambient and fluid temperature | $0^{\circ}$ to $60^{\circ} \mathrm{C}$ (No freezing) |  |  |  |  |
| Cushion | Not attached |  |  |  |  |
| Angle adjustment range | Rotation end $\pm 5^{\circ}$ |  |  |  |  |
| Rotation angle | $80^{\circ}$ to $100^{\circ}, 170^{\circ}$ to $190^{\circ}$ |  |  |  |  |
| Port size | M5 x 0.8 |  | Rc $1 / 8, \mathrm{G} 1 / 8$, NPT $1 / 8$, NPTF $1 / 8$ |  |  |
| Output (N•m) ${ }^{\text {Note) }}$ | 0.30 | 0.75 | 1.8 | 3.1 | 5.3 |

Note) Output under operating pressure at 0.5 MPa . Refer to page 4 for further information.

## Allowable Kinetic Energy and Rotation Time Adjustment Range

| Size | Allowable kinetic energy (J) | Stable operational rotation time adjustment range $\left(\mathrm{s} / 90^{\circ}\right)$ |
| :---: | :---: | :---: |
| $\mathbf{1 0}$ | 0.00025 |  |
| $\mathbf{1 5}$ | 0.00039 | 0.7 to 5 |
| $\mathbf{2 0}$ | 0.025 |  |
| $\mathbf{3 0}$ | 0.048 |  |
| $\mathbf{4 0}$ | 0.081 | 1 to 5 |

Note) If operated with kinetic energy exceeding the allowable value, may cause damage to the internal parts and result in product failure. Please pay special attention to the kinetic energy levels when designing, adjusting and during operation to avoid exceeding the allowable limit.

## Weight

| Size | $(\mathrm{g})$ |  |
| :---: | :---: | :---: |
|  | $90^{\circ}$ | Standard weight Note) |
| 10 | 120 | $180^{\circ}$ |
| 15 | 220 | 150 |
| 20 | 600 | 270 |
| 30 | 900 | 700 |
| 40 | 1400 | 1100 |

[^1]
## Series CRQ2X

## Rotation Range

When pressurized from the port indicated by the arrow, the shaft will rotate in a clockwise direction.

Rotation angle: $90^{\circ}$


Rotation angle: $\mathbf{1 8 0}^{\boldsymbol{\circ}}$


# Low-Speed Compact Rotary Actuator Rack \& Pinion Type 

Series CRQ2X

Construction

Standard
Sizes 10/15



Component Parts

| No. | Description | Material |
| :---: | :--- | :---: |
| $\mathbf{1}$ | Body | Aluminum alloy |
| $\mathbf{2}$ | Cover | Aluminum alloy |
| $\mathbf{3}$ | Plate | Aluminum alloy |
| $\mathbf{4}$ | End cover | Aluminum alloy |
| $\mathbf{5}$ | Piston | Stainless steel |
| $\mathbf{6}$ | Size: 10, 15 | Stainless steel |
|  | Size: $\mathbf{2 0}, \mathbf{3 0}, \mathbf{4 0}$ | Shaft |
| $\mathbf{7}$ | Seal retainer |  |
| $\mathbf{8}$ | Bearing retainer | Aluminum alloy |
| $\mathbf{9}$ | Wear ring | Aluminum alloy |
| $\mathbf{1 0}$ | Hexagon socket head cap screw | Resin |
| $\mathbf{1 1}$ | Hexagon nut with flange | Stainless steel |
| $\mathbf{1 2}$ | Cross recessed screw No. 0 | Steel wire |

## Standard

Sizes 20/30/40


Component Parts

| No. | Description |  |  | Material |
| :---: | :---: | :---: | :---: | :---: |
| 13 | Size: 10, 15 | Cross recessed screw No. 0 |  | Steel wire |
|  | Size: 20, 30, 40 | Cross recessed screw |  |  |
| 14 | Hexagon socket head set screw |  |  | Chrome molybdenum steel |
| 15 | Bearing |  |  | Bearing steel |
| 16 | Size: 20, 30, 40 only |  | Parallel key | Carbon steel |
| 17 | Size: 20, 30, 40 only |  | Steel ball | Stainless steel |
| 18 | CS-type retaining ring |  |  | Stainless steel |
| 19 | Seal |  |  | NBR |
| 20 | Gasket |  |  | NBR |
| 21 | Piston seal |  |  | NBR |
| 22 | Seal washer |  |  | NBR |
| 23 | With auto switch only |  | Magnet | - |

## Replacement Parts

| Description | Part no. |  |  |  | Note |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{1 0}$ | $\mathbf{1 5}$ | $\mathbf{2 0}$ | $\mathbf{3 0}$ |  |  |
| Seal kit | $\mathrm{P} 473010-23$ | $\mathrm{P} 473020-23$ | $\mathrm{P} 473030-23$ | $\mathrm{P} 473040-23$ | $\mathrm{P} 473050-23$ | A set of above numbers (9), (19, (20, (21) and (22) |

## Series CRQ2X

Construction

With auto switch Sizes 10/15


With auto switch
Sizes 20/30/40


## Dimensions

Sizes 10/15


| Size | Rotation angle | A | $\mathbf{A U}^{\text {Note) }}$ | B | BA | BB | BC | BD | BU | $\underset{(\mathrm{g} 6)}{\mathrm{D}}$ | $\begin{gathered} \text { DD } \\ \text { (h9) } \end{gathered}$ | H |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 10 | $90^{\circ}, 180^{\circ}$ | 42 | (8.5) | 29 | 8.5 | 17 | 6.7 | 2.2 | 16.7 | 5 | 12 | 18 |
| 15 | $90^{\circ}, 180^{\circ}$ | 53 | (9.5) | 31 | 9 | 26.4 | 10.6 | - | 23.1 | 6 | 14 | 20 |


| Size | Rotation angle | W | Q | S | US | UW | ab | M | TA | TC | TD |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 10 | $90^{\circ}$ | 4.5 | 17 | 56 | 35 | 44 | 6 | 9 | 15.5 | 8 | 15.4 |
|  | $180^{\circ}$ |  |  | 69 |  |  |  |  |  |  |  |
| 15 | $90^{\circ}$ | 5.5 | 20 | 65 | 40 | 50 | 7 | 10 | 16 | 9 | 17.6 |
|  | $180^{\circ}$ |  |  | 82 |  |  |  |  |  |  |  |

Note) The AU dimension is not the dimension at the time of shipment, since its dimension is for adjustment parts.

## Series CRQ2X

Dimensions

## Sizes 20/30/40

## With double shaft




| Size | Rotation angle | A | $\begin{gathered} \text { Note 1) }^{\text {AU }} \end{gathered}$ | B | BA | BB | BC | BD | BE | BU | $\underset{\text { (g6) }}{\text { D }}$ | $\begin{gathered} \text { DD } \\ \text { (h9) } \end{gathered}$ | F | H | J | JA | JB | JJ | K |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 20 | $90^{\circ}, 180^{\circ}$ | 63 | (11) | 50 | 14 | 34 | 14.5 | - | - | 30.4 | 10 | 25 | 2.5 | 30 | M8 x 1.25 | 11 | 6.5 | - | 3 |
| 30 | $90^{\circ}, 180^{\circ}$ | 69 | (11) | 68 | 14 | 39 | 16.5 | 49 | 16 | 34.7 | 12 | 30 | 3 | 32 | M10 $\times 1.5$ | 14 | 8.5 | M5 x 0.8 depth 6 | 4 |
| 40 | $90^{\circ}, 180^{\circ}$ | 78 | (13) | 76 | 16 | 47 | 18.5 | 55 | 16 | 40.4 | 15 | 32 | 3 | 36 | M10 $\times 1.5$ | 14 | 8.6 | M6 $\times 1$ depth 7 | 5 |


| Size | Rotation angle | Q | S | W | Keyway dimensions |  | US | TA | TB | TC | TD | $\begin{gathered} \text { TF } \\ \text { (H9) } \end{gathered}$ | $\begin{gathered} \text { TG } \\ \text { (H9) } \end{gathered}$ | TL | UW | G | M | N | L |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | b | 1 |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 20 | $90^{\circ}$ | 29 | 104 | 11.5 | $4_{-0.03}^{0}$ | 20 | 59 | 24.5 | 1 | 13.5 | 27 | 4 | 4 | 2.5 | 74 | $8{ }_{-0.1}^{0}$ | 15 | 11 | $9.6{ }_{-0.1}^{0}$ |
|  | $180^{\circ}$ |  | 130 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 30 | $90^{\circ}$ | 33 | 122 | 13.5 | $4_{-0.03}^{0}$ | 20 | 65 | 27 | 2 | 19 | 36 | 4 | 4 | 2.5 | 83 | $10_{-0.1}^{0}$ | 18 | 13 | $11.4-0.1$ |
|  | $180^{\circ}$ |  | 153 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 40 | $90^{\circ}$ | 37 | 139 | 17 | $5_{-0.03}^{0}$ | 25 | 73 | 32.5 | 2 | 20 | 39.5 | 5 | 5 | 3.5 | 93 | $11{ }_{-0.1}^{0}$ | 20 | 15 | $14 \stackrel{0}{-0.1}$ |
|  | $180^{\circ}$ |  | 177 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

Note 1) The AU dimension is not the dimension at the time of shipment, since its dimension is for adjustment parts.
S: Upper $90^{\circ}$, Lower $180^{\circ}$ Note 2) In addition to Rc 1/8; G 1/8, NPT 1/8 and NPTF $1 / 8$ are also available.

## Unit Used as Flange Mount

The body's L dimensions are shown in the table below. When JIS standard hexagon socket head cap screws are used, the grooves should be used to contain the heads of the screws.


| Size | $\mathbf{L}$ | Screw |
| :---: | :---: | :---: |
| $\mathbf{1 0}$ | 13 | M4 |
| $\mathbf{1 5}$ | 16 | M4 |
| $\mathbf{2 0}$ | 22.5 | M6 |
| $\mathbf{3 0}$ | 24.5 | M8 |
| $\mathbf{4 0}$ | 28.5 | M8 |

Auto Switch Proper Mounting Position (at Rotation End Detection)


| Size | Rotation angle | Reed switch |  |  |  | Solid state switch |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | A | B | Operating angle ( $\theta$ m) | $\begin{array}{\|l\|l\|} \hline \text { Hystere- } \\ \text { sis } \\ \text { angle } \end{array}$ | A | B | Operating angle ( $\theta$ m) | $\begin{aligned} & \text { Hystere- } \\ & \text { sys } \\ & \text { angle } \end{aligned}$ |
| 10 | $90^{\circ}$ | 15 | 21.5 | $63^{\circ}$ | $12^{\circ}$ | 19 | 25.5 | $75^{\circ}$ | $3^{\circ}$ |
|  | $180^{\circ}$ | 18 | 31 |  |  | 22 | 35 |  |  |
| 15 | $90^{\circ}$ | 18.5 | 27 | $52^{\circ}$ | $9^{\circ}$ | 22.5 | 31 | $69^{\circ}$ | $3^{\circ}$ |
|  | $180^{\circ}$ | 22.5 | 39.5 |  |  | 26.5 | 43.5 |  |  |
| 20 | $90^{\circ}$ | 36 | 48.5 | $41^{\circ}$ | $9^{\circ}$ | 40 | 52.5 | $56^{\circ}$ | $4^{\circ}$ |
|  | $180^{\circ}$ | 42 | 67.5 |  |  | 46 | 71.5 |  |  |
| 30 | $90^{\circ}$ | 43 | 59 | $32^{\circ}$ | $7^{\circ}$ | 47 | 63 | $43^{\circ}$ | $3^{\circ}$ |
|  | $180^{\circ}$ | 51 | 82 |  |  | 55 | 86 |  |  |
| 40 | $90^{\circ}$ | 50 | 69 | $24^{\circ}$ | $5^{\circ}$ | 54 | 73 | $36^{\circ}$ | $4^{\circ}$ |
|  | $180^{\circ}$ | 59.5 | 97.5 |  |  | 63.5 | 101.5 |  |  |

Operating angle $\theta \mathrm{m}$ : Value of the operating range of single auto switch (Lm) as represented by rotation angle for shaft.
Hysteresis angle: Value of the auto switch hysteresis as represented by angle.

Note) For actual setting, adjustment shall be made after checking the auto switch operating condition.

## Low-Speed Rotary Table Rack \& Pinion Type

 Series MSQX Sizes: 10, 20, 30, 50How to Order


Applicable Auto Switches/Refer to pages 24 through to 27 for further information on auto switches.

| $\stackrel{\otimes}{\stackrel{\circ}{\sim}}$ | Special function | Electrical entry |  | Wiring (Output) | Load voltage |  |  | Auto switch model |  | Lead wire length ( $m$ ) Note 1) |  |  |  | Applicable load |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | DC |  | AC |  |  | $\begin{gathered} 0.5 \\ \text { (Nil) } \end{gathered}$ | $\begin{gathered} 1 \\ (\mathrm{M}) \end{gathered}$ | $\begin{gathered} 3 \\ (\mathrm{~L}) \end{gathered}$ | $\begin{gathered} 5 \\ (\mathrm{Z}) \end{gathered}$ |  |  |
|  |  |  |  |  |  |  | Perpendicular | In-line |  |  |  |  |  |  |
|  |  | Grommet | Yes | 3-wire (NPN) | 24 V | $5 \mathrm{~V}, 12 \mathrm{~V}$ |  | $-$ | M9NV | M9N | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | IC | Relay, PLC |
|  | - |  |  | 3-wire (PNP) |  |  | M9PV |  | M9P | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | circuit |  |
|  |  |  |  | 2-wire |  | 12 V | M9BV |  | M9B | $\bigcirc$ | - | $\bigcirc$ | $\bigcirc$ | - |  |
|  | Diagnostic indication (2-colour) |  |  | 3-wire (NPN) |  | $5 \mathrm{~V}, 12 \mathrm{~V}$ | M9NWV |  | M9NW | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | C |  |
|  |  |  |  | 3-wire (PNP) |  |  | M9PWV |  | M9PW | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | circuit |  |
|  |  |  |  | 2-wire |  | 12 V | M9BWV |  | M9BW | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - |  |
|  | Water resistant (2-colour) |  |  | 3-wire (NPN) |  | $5 \mathrm{~V}, 12 \mathrm{~V}$ | M9NAV |  | M9NA | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | IC circuit |  |
|  |  |  |  | 3-wire (PNP) |  |  | M9PAV |  | M9PA | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ |  |  |
|  |  |  |  | 2-wire |  | 12 V | M9BAV |  | M9BA | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | $\bigcirc$ | - |  |
|  | - | Grommet | No | 2-wire | 24 V | 12 V | 100 V or less | A90V | A90 | $\bigcirc$ | - | $\bigcirc$ | - | IC circuit | Relay, PLC |  |
|  |  |  | Yes | 3-wire <br> (NPN equiv.) | - | 5 V | - | A96V | A96 | $\bigcirc$ | - | $\bigcirc$ | - |  | - |  |
|  |  |  |  | 2-wire | 24 V | 12 V | 100 V | A93V | A93 | $\bigcirc$ | - | $\bigcirc$ | - | - | Relay, PLC |  |
| Note 1) Lead wire length symbols: |  |  |  | $\begin{gathered} 0.5 \mathrm{~m} \ldots . . . \mathrm{Nil} \\ 1 \mathrm{~m} \ldots . . \mathrm{M} \\ 3 \mathrm{~m} \ldots . . \mathrm{L} \\ 5 \mathrm{~m} \ldots . . \mathrm{Z} \end{gathered}$ | (Example) M9NW M9NWM M9NWL M9NWZ |  |  |  |  |  |  |  |  |  |  |  |

Note 2) Although it is possible to mount water resistant type auto switches, note that the rotary actuator itself is not water resistant.

- Auto switches marked with "○" are manufactured upon a receipt of order
- For details about auto switches with pre-wired connector, refer to "SMC Best Pneumatics 2004" Vol. 11 catalogue.
- Auto switches are shipped together, but not assembled.

[^2]- -50 Without indicator light
-61 Flexible lead wire
- Pre-wired connector


## Specifications



| Size |  | 10 | 20 | 30 | 50 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Fluid |  | Air (Non-lube) |  |  |  |
| Max. operating pressure |  | 1 MPa |  |  |  |
| Min. operating pressure |  | 0.1 MPa |  |  |  |
| Ambient and fluid temperature |  | $0^{\circ}$ to $60^{\circ} \mathrm{C}$ (No freezing) |  |  |  |
| Cushion |  | Not attached |  |  |  |
| Angle adjustment range |  | 0 to $190^{\circ}$ |  |  |  |
| Maximum rotation angle |  | $190^{\circ}$ |  |  |  |
| Port size | End port | M5 x 0.8 |  | Rc $1 / 8, \mathrm{G} 1 / 8$, NPT $1 / 8$, NPTF $1 / 8$ |  |
|  | Side port | M5 x 0.8 |  |  |  |
| Output (N•m) ${ }^{\text {Note) }}$ |  | 0.89 | 1.8 | 2.7 | 4.6 |

Note) Output under the operating pressure at 0.5 MPa . Refer to page 4 for further information.

## JIS Symbol



## Allowable Kinetic Energy and Rotation Time Adjustment Range

| Size | Allowable kinetic energy $(\mathrm{J})$ | Stable operational rotation time adjustment range $\left(\mathrm{s} / 90^{\circ}\right)$ |
| :---: | :---: | :---: |
| $\mathbf{1 0}$ | 0.007 |  |
| $\mathbf{2 0}$ | 0.025 | 1 to 5 |
| $\mathbf{3 0}$ | 0.048 |  |
| $\mathbf{5 0}$ | 0.081 |  |

Note) If operated where the kinetic energy exceeds the allowable value, this may cause damage to the internal parts and result in product failure. Please pay special attention to the kinetic energy levels when designing, adjusting and during operation to avoid exceeding the allowable limit.

## Weight

| (g) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Size | $\mathbf{1 0}$ | $\mathbf{2 0}$ | $\mathbf{3 0}$ | $\mathbf{5 0}$ |
| Basic | 530 | 990 | 1290 | 2080 |

[^3]
## Series MSQX

## Rotation Direction and Rotation Angle

- The rotary table turns in the clockwise direction when the A port is pressurized, and in the counter-clockwise direction when the B port is pressurized.
- By adjusting the adjustment bolt, the rotation end can be set within the range shown in the drawing for the desired rotation angle.


With Adjustment Bolt

| Size | Adjustment angle per rotation of <br> angle adjustment screw |
| :---: | :---: |
| $\mathbf{1 0}$ | $10.2^{\circ}$ |
| $\mathbf{2 0}$ | $7.2^{\circ}$ |
| $\mathbf{3 0}$ | $6.5^{\circ}$ |
| $\mathbf{5 0}$ | $8.2^{\circ}$ |



Note) - The drawing shows the rotation range of the positioning pin hole.

- The pin hole position in the drawing shows the counter-clockwise rotation end when the adjustment bolts $A$ and $B$ are tightened equally and the rotation is adjusted $180^{\circ}$.


## Rotation Angle Range Example

- Various rotation ranges are possible, as shown in the drawings below, using adjustment bolts $A$ and $B$. (The drawings also show the rotation ranges of the positioning pin hole.)
- The rotation angle can also be set on a type with inertial absorber.



## Low-Speed Rotary Table Rack \& Pinion Type

Table Displacement (Reference values)

- The following graphs show the displacement at point $A$, which is 100 mm apart from the centre of rotation, where the load is applied.





MSQXB50A


## Series MSQX

Construction


Component Parts

| No. | Description | Material |
| :---: | :--- | :---: |
| $\mathbf{1}$ | Body | Aluminium alloy |
| $\mathbf{2}$ | Cover | Aluminium alloy |
| $\mathbf{3}$ | Plate | Resin |
| $\mathbf{4}$ | Seal | NBR |
| $\mathbf{5}$ | End cover | Aluminium alloy |
| $\mathbf{6}$ | Piston | Stainless steel |
| $\mathbf{7}$ | Pinion | Chrome molybdenum steel |
| $\mathbf{8}$ | Hexagon nut with flange | Steel wire |
| 9 | Adjustment bolt | Chrome molybdenum steel |
| $\mathbf{1 0}$ | Seal retainer | Aluminium alloy |
| $\mathbf{1 1}$ | Gasket | NBR |
| $\mathbf{1 2}$ | Gasket | NBR |
| $\mathbf{1 3}$ | Table | Aluminium alloy |
| $\mathbf{1 4}$ | Bearing retainer | Aluminium alloy |

Component Parts

| No. | Description | Material |
| :---: | :--- | :---: |
| $\mathbf{1 5}$ | Magnet | - |
| $\mathbf{1 6}$ | Wear ring | Resin |
| $\mathbf{1 7}$ | Piston seal | NBR |
| $\mathbf{1 8}$ | Deep groove ball bearing | Bearing steel |
| $\mathbf{1 9}$ | Deep groove ball bearing | Bearing steel |
| $\mathbf{2 0}$ | Cross recessed screw No. $\mathbf{0}$ | Steel wire |
| $\mathbf{2 1}$ | Cross recessed screw | Size: $\mathbf{1 0}$ |
|  | Low head cap screw | Size: $\mathbf{2 0}$ to $\mathbf{5 0}$ |
| $\mathbf{2 2}$ | Hexagon socket head cap screw | Chrome molybdenum steel |
| $\mathbf{2 3}$ | Hexagon socket head cap screw | Stainless steel |
| $\mathbf{2 4}$ | CS-type retaining ring | Stainless steel |
| $\mathbf{2 5}$ | Parallel pin | Spring steel |
| $\mathbf{2 6}$ | Seal washer | Size: $\mathbf{1 0}$ to $\mathbf{5 0}$ |
| $\mathbf{2 7}$ | Plug | Carbon steel |
|  |  |  |

## Replacement Parts

| Description | Part no. |  |  | Note |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{1 0}$ | $\mathbf{2 0}$ | $\mathbf{3 0}$ |  |  |
| Seal kit | P523010-20 | P523020-20 | P523030-20 | P523040-20 | A set of above numbers (4), (11), (12), (16), (17) and (26) |

## Dimensions

Basic: MSQXB $\square A$


| Size | AA | A | AU | AV | AW | AX | AY | BA | BB | BC | BD | BE | CA | CB | D | DD | DE | DF | DG | FA | FB | FC | FD | H | J | JA | JB |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 10 | 55.4 | 50 | 8.6 | 20 | 15.5 | 12 | 4 | 9.5 | 34.5 | 27.8 | 60 | 27 | 4.5 | 28.5 | 45h9 | 46h9 | 20H9 | 6 | 15H9 | 8 | 4 | 3 | 4.5 | 13 | 6.8 | 11 | 6.5 |
| 20 | 70.8 | 65 | 10.6 | 27.5 | 16 | 14 | 5 | 12 | 46 | 30 | 76 | 34 | 6 | 30.5 | 60h9 | 61h9 | 28H9 | 9 | 17H9 | 10 | 6 | 2.5 | 6.5 | 17 | 8.6 | 14 | 8.5 |
| 30 | 75.4 | 70 | 10.6 | 29 | 18.5 | 14 | 5 | 12 | 50 | 32 | 84 | 37 | 6.5 | 33.5 | 65h9 | 67h9 | 32H9 | 12 | 22H9 | 10 | 4.5 | 3 | 6.5 | 17 | 8.6 | 14 | 8.5 |
| 50 | 85.4 | 80 | 14 | 38 | 22 | 19 | 6 | 15.5 | 63 | 37.5 | 100 | 50 | 10 | 37.5 | 75h9 | 77h9 | 35H9 | 13 | 26H9 | 12 | 5 | 3 | 7.5 | 20 | 10.5 | 18 | 10.5 |


| Size | JC | JD | JJ | JU | P | Q | S | SD | SE | SF | SU | UU | WA | WB | WC | WD | WE | WF | XA | XB | XC | YA | YB | YC |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 10 | M $8 \times 1.25$ | 12 | M5 x 0.8 | M $8 \times 1$ | M5 x 0.8 | 34 | 92 | 9 | 13 | 45 | 17.7 | 47 | 15 | 3H9 | 3.5 | M5 x 0.8 | 8 | 32 | 27 | 3H9 | 3.5 | 19 | 3H9 | 3.5 |
| 20 | $\mathrm{M} 10 \times 1.5$ | 15 | M6x 1 | M10 $\times 1$ | M5 x 0.8 | 37 | 117 | 10 | 12 | 60 | 25 | 54 | 20.5 | 4H9 | 4.5 | M6x 1 | 10 | 43 | 36 | 4H9 | 4.5 | 24 | 4H9 | 4.5 |
| 30 | $\mathrm{M} 10 \times 1.5$ | 15 | M6 x 1 | M10 $\times 1$ | Rc $1 / 8$ Note) | 40 | 127 | 11.5 | 14 | 65 | 25 | 57 | 23 | 4H9 | 4.5 | M6 x 1 | 10 | 48 | 39 | 4H9 | 4.5 | 28 | 4H9 | 4.5 |
| 50 | M12 $\times 1.75$ | 18 | M8 x 1.25 | M14 $\times 1.5$ | Rc 1/8 Note) | 46 | 152 | 14.5 | 15 | 75 | 31.4 | 66 | 26.5 | 5 H 9 | 5.5 | M8 $\times 1.25$ | 12 | 55 | 45 | 5H9 | 5.5 | 33 | 5H9 | 5.5 |

Note) In addition to Rc 1/8; G 1/8, NPT 1/8 and NPTF 1/ 8 are also available.

## Series MSQX

## Auto Switch Proper Mounting Position (at Rotation End Detection)



| Size | Rotation <br> angle | Reed switch |  |  |  |  | Solid state switch |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\mathbf{B}$ | Operating angle <br> $(\theta \mathbf{~ m})$ | Hysteresis <br> angle | $\mathbf{A}$ | $\mathbf{B}$ | Operating angle <br> $(\theta \mathbf{~ m})$ | Hysteresis <br> angle |  |  |
| $\mathbf{1 0}$ | $190^{\circ}$ | 17 | 36 | $90^{\circ}$ | $10^{\circ}$ | 21 | 40 | $60^{\circ}$ | $10^{\circ}$ |  |
| $\mathbf{2 0}$ | $190^{\circ}$ | 23 | 50 | $80^{\circ}$ | $10^{\circ}$ | 27 | 54 | $50^{\circ}$ | $10^{\circ}$ |  |
| $\mathbf{3 0}$ | $190^{\circ}$ | 27 | 56 | $65^{\circ}$ | $10^{\circ}$ | 31 | 60 | $50^{\circ}$ | $10^{\circ}$ |  |
| $\mathbf{5 0}$ | $190^{\circ}$ | 33 | 68 | $50^{\circ}$ | $10^{\circ}$ | 37 | 72 | $40^{\circ}$ | $10^{\circ}$ |  |

Operating angle $\theta \mathbf{m}$ : Value of the operating range of single auto switch (Lm) as represented by rotation angle for shaft. Hysteresis angle: Value of the auto switch hysteresis as represented by angle.
Note) For actual setting, adjustment shall be made after checking the auto switch operating condition.

## Series CRQ2X/MSQX <br> Auto Switch Specifications

Auto Switch Common Specifications

| Type | Reed switch | Solid state switch |  |
| :--- | :---: | :---: | :---: |
| Leakage current | None | 3-wire: $100 \mu \mathrm{~A}$ or less 2 -wire: 0.8 mA or less |  |
| Operating time | 1.2 ms | 1 ms or less |  |
| Impact resistance | $300 \mathrm{~m} / \mathrm{s}^{2}$ | $1000 \mathrm{~m} / \mathrm{s}^{2}$ |  |
| Insulation resistance | $50 \mathrm{M} \Omega$ or more at 500 VDC Mega (between lead wire and case) |  |  |
| Withstand voltage | 1500 VAC for 1 minute (between lead wire and case) | 1000 VAC for 1 minute (between lead wire and case) |  |
| Ambient temperature | -10 to $60^{\circ} \mathrm{C}$ |  |  |
| Enclosure | IEC60529 standard IP67, JIS C 0920 waterproof construction |  |  |
| Standard | Conforming to CE Standard |  |  |

## Lead Wire Length

## Lead wire length indication



Note 1) Applicable auto switch with 5 m lead wire: " $Z$ "
Solid state switch: Manufactured upon receipt of order as standard.
Note 2) To designate solid state switches with flexible specifications, add "-61" after the lead wire length. Flexible cable is used for $\mathrm{D}-\mathrm{M} 9 \square(\mathrm{~V})$, D M9 $\square \mathrm{W}(\mathrm{V}), \mathrm{D}-\mathrm{M} 9 \square \mathrm{~A}(\mathrm{~V})$ as standard. There is no need to place the suffix -61 to the end of part number.
Note 3) $1 \mathrm{~m}(\mathrm{M}): \mathrm{D}-\mathrm{M} 9 \square \mathrm{~W}, \mathrm{D}-\mathrm{M} 9 \square \mathrm{~A}(\mathrm{~V})$.
Note 4) Lead wire length tolerance

| Lead wire length | Tolerance |
| :---: | ---: |
| 0.5 m | $\pm 15 \mathrm{~mm}$ |
| 1 m | $\pm 30 \mathrm{~mm}$ |
| 3 m | $\pm 90 \mathrm{~mm}$ |
| 5 m | $\pm 150 \mathrm{~mm}$ |

## Contact Protection Box: CD-P11, CD-P12

## <Applicable switch model>

D-A9 $\square(\mathrm{V}$ ) type
The above auto switch type does not have a built-in contact protection circuit.
(1) Where the operation load is an inductive load.
(2) Where the wiring length to load is greater than $5 \mathbf{~ m}$.
(3) Where the load voltage is $\mathbf{1 0 0}$ VAC.

Therefore, use a contact protection box with the switch for any of the above cases:
The contact life may be shortened (due to permanent energizing conditions). Since the solid state auto switch is a semiconductor switch which has no contacts, no contact protection box is needed.
(4) Where the load voltage is $\mathbf{1 1 0}$ VAC.

When the load voltage is increased by more than $10 \%$ to the rating of applicable auto switches above, use a contact protection box (CD-P11) to reduce the upper limit of the load current by $10 \%$ so that it can be set within the range of the load current range.

## Specifications

| Part no. | CD-P11 |  | CD-P12 |
| :--- | :---: | :---: | :---: |
| Load voltage | 100 VAC | 200 VAC | 24 VDC |
| Max. load current | 25 mA | 12.5 mA | 50 mA |

$\begin{array}{ll}\text { Note) Lead wire length - Switch connection side } & 0.5 \mathrm{~m} \\ & \text { Load connection side } \\ 0.5 \mathrm{~m}\end{array}$


Internal Circuit


## Dimensions



## Connection

To connect a switch unit to a contact protection box, first connect the lead wire
from the side of the contact protection box marked SWITCH to the lead wire coming out of the switch unit. Keep the switch as close as possible to the contact protection box, with a lead wire length of no more than 1 meter.

# Auto Switch <br> Connections and Examples 

## Basic Wiring

Solid state 3-wire, NPN


Solid state 3-wire, PNP


(Solid state)


## 2-wire

(Reed switch)


Power supplies for switch and load are separate.)


## Example of Connection to PLC (Programmable Logic Controller)

- Sink input specification 3-wire, NPN

- Source input specification

3-wire, PNP


2-wire


## 2-wire



Connect according to the applicable PLC input specifications, as the connection method will vary depending on the PLC input specifications.

## Connection examples for AND (Serial) and OR (Parallel)

- 3-wire

AND connection for NPN output (using relays)


## 2-wire with 2-switch AND connection



When two switches are connected in series, a load may malfunction because the load voltage will decline when in the ON state.
The indicator lights will illuminate if both of the switches are in the ON state.

Load voltage at $\mathrm{ON}=\begin{gathered}\text { Power supply } \\ \text { voltage }\end{gathered}-\underset{\text { Residual }}{\text { voltage }} \times 2$ pcs.

$$
=24 \mathrm{~V}-4 \mathrm{~V} \times 2 \mathrm{pcs} .
$$

$$
=16 \mathrm{~V}
$$

Example: Power supply is 24 VDC.
Internal voltage drop in switch is 4 V .

AND connection for NPN output (performed with switches only)


The indicator lights will illuminate when both switches are turned ON.

## 2-wire with 2-switch OR connection



OR connection for NPN output

(Reed)
Because there is no current leakage, the load voltage will not increase when turned OFF. However, depending on the number of switches in the ON state, the indicator lights may sometimes get dark or not light up, because of the dispersion and reduction of the current flowing to the switches.

# Reed Switch: Direct Mounting Style D-A90(V)/D-A93(V)/D-A96(V) ( E 

## Grommet



## ©Caution

## Precautions

Fix the switch with the existing screw installed on the switch body. The switch may be damaged if a screw, other than the one supplied, is used different.

Auto Switch Internal Circuit


D-A93(V)


D-A96(V)


Note) (1) In case where the operation load is an inductive load.
(2) In case where the wiring load is greater than 5 m .
(3) In case where the load voltage is 100 VAC.
Use the auto switch with a contact protection box in any of the above mentioned cases. (For details about the contact protection box, refer to page 22.)

## Auto Switch Specifications

| PLC: Programmable Logic Controller |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| D-A90/D-A90V (Without indicator light) |  |  |  |  |  |  |
| Auto switch part no. | D-A90 | D-A90V | D-A90 | D-A90V | D-A90 | D-A90V |
| Electrical entry direction | In-line | Perpendicular | In-line | Perpendicular | In-line | Perpendicular |
| Applicable load | IC circuit, Relay, PLC |  |  |  |  |  |
| Load voltage | 24 VAC/DC or less |  | $48 \mathrm{VAC} / \mathrm{DC}$ or less |  | $100 \mathrm{VAC/DC}$ or less |  |
| Maximum load current | 50 mA |  | 40 mA |  | 20 mA |  |
| Contact protection circuit | None |  |  |  |  |  |
| Internal resistance | $1 \Omega$ or less (including lead wire length of 3 m ) |  |  |  |  |  |
| Standard | Conforming to CE Standard |  |  |  |  |  |
| D-A93/D-A93V/D-A96/D-A96V (With indicator light) |  |  |  |  |  |  |
| Auto switch part no. | D-A93 | D-A93V | D-A93 | D-A93V | D-A96 | D-A96V |
| Electrical entry direction | In-line | Perpendicular | In-line | Perpendicular | In-line | Perpendicular |
| Applicable load | Relay, PLC |  |  |  | IC circuit |  |
| Load voltage | 24 VDC |  | 100 VAC |  | 4 to 8 VDC |  |
| Load current range and max. load current | 5 to 40 mA |  | 5 to 20 mA |  | 20 mA |  |
| Contact protection circuit | None |  |  |  |  |  |
| Internal voltage drop | D-A93 - 2.4 V or less (to 20 mA )/3 V or less (to 40 mA ) D-A93V - 2.7 V or less |  |  |  | 0.8 V or less |  |
| Indicator light | Red LED illuminates when turned ON |  |  |  |  |  |
| Standard | Conforming to CE Standard |  |  |  |  |  |

- Lead wires

D-A90(V)/D-A93(V) $\rightarrow$ Oilproof heavy-duty vinyl cable: ø2.7, $0.18 \mathrm{~mm}^{2} \times 2$ cores (Brown, Blue), 0.5 m D-A96(V) $\rightarrow$ Oilproof heavy-duty vinyl cable: $\varnothing 2.7,0.15 \mathrm{~mm}^{2} \times 3$ cores (Brown, Black, Blue), 0.5 m
Note 1) Refer to page 22 for reed switch common specifications.
Note 2) Refer to page 22 for lead wire lengths.
Note 3) If load current is less than 5 mA , the visibility of the indicator light is decreased. If less than 2.5 mA , the light may become invisible. From the point of view of contact output, however, it is not a problem as long as the load current is more than 1 mA .

## Weight

Unit: g

| Auto switch part no. |  | D-A90(V) | D-A93(V) | D-A96(V) |
| :---: | :---: | :---: | :---: | :---: |
| Lead wire length <br> $(\mathrm{m})$ | 0.5 | 6 | 6 | 8 |
|  | 3 | 30 | 30 | 41 |

Dimensions
Unit: mm
D-A90/A93/A96

M2.5 x $4 \ell$
Slotted set screw

(24.5) Indicator light

D-A90 type comes without indicator light.
Oen
10 Most sensitive position
( ): dimensions for D-A93
D-A90V/A93V/A96V


Indicator light
D-A90V type comes without indicator light.

# Solid State Switch: Direct Mounting Style D-M9N(V)/D-M9P(V)/D-M9B(V) C E 

## Grommet

- 2-wire load current is reduced ( 2.5 to 40 mA ).
- UL certified (style 2844) lead cable is used.
- Flexibility is 1.5 times greater than the conventional model (SMC comparison).
- Using flexible cable as standard spec.
- Brightness of indicator light is 2 times greater than the conventional model (SMC comparison).


## $\triangle$ Caution

## Precautions

Fix the switch with the existing screw installed on the switch body. The switch may be damaged if a screw, other than the one supplied, is used different.

## Auto Switch Internal Circuit



## Auto Switch Specifications

| PLC: Programmable Logic Controller |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| D-M9 $\square$ /D-M9 $\square$ V (With indicator light) |  |  |  |  |  |  |
| Auto switch part no. | D-M9N | D-M9NV | D-M9P | D-M9PV | D-M9B | D-M9BV |
| Electrical entry direction | In-line | Perpendicular | In-line | Perpendicular | In-line | Perpendicular |
| Wiring type | 3-wire |  |  |  | 2-wire |  |
| Output type | NPN |  | PNP |  | - |  |
| Applicable load | IC circuit, Relay, PLC |  |  |  | 24 VDC relay, PLC |  |
| Power supply voltage | 5, 12, 24 VDC ( 4.5 to 28 V ) |  |  |  | - |  |
| Current consumption | 10 mA or less |  |  |  | - |  |
| Load voltage | 28 VDC or less |  | - |  | 24 VDC (10 | to 28 VDC$)$ |
| Load current | 40 mA or less |  |  |  | 2.5 to 40 mA |  |
| Internal voltage drop | 0.8 V or less |  |  |  | 4 V or less |  |
| Leakage current | $100 \mu \mathrm{~A}$ or less at 24 VDC |  |  |  | 0.8 mA or less |  |
| Indicator light | Red LED illuminates when turned ON. |  |  |  |  |  |
| Standard | Conforming to CE Standard |  |  |  |  |  |

- Lead wires $\rightarrow$ Oilproof heavy-duty vinyl cable: $ø 2.7 \times 3.2$ ellipse D-M9B(V) $\quad 0.15 \mathrm{~mm}^{2} \times 2$ cores
D-M9N(V), D-M9P(V) $\quad 0.15 \mathrm{~mm}^{2} \times 3$ cores
Note 1) Refer to page 22 for solid state switch common specifications.
Note 2) Refer to page 22 for lead wire lengths.


## Weight

Unit: g

| Auto switch part no. |  | D-M9N(V) | D-M9P(V) | D-M9B(V) |
| :---: | :--- | :---: | :---: | :---: |
| Lead wire length <br> $(\mathrm{m})$ | 0.5 | 8 | 8 | 7 |
|  | 3 | 41 | 41 | 38 |
|  | 5 | 68 | 68 | 63 |

## Dimensions



# 2-Color Indication Solid State Switch: Direct Mounting Style D-M9NW(V)/D-M9PW(V)/D-M9BW(V) ( E 

## Grommet

- 2-wire load current is reduced ( 2.5 to 40 mA ).
- UL certified (style 2844) lead cable is used.
- Flexibility is 1.5 times greater than the conventional model (SMC comparison).
- Using flexible cable as standard spec. - The optimum operating position can be determined by the colour of the light. (Red $\rightarrow$ Green $\leftarrow$ Red)
- Brightness of indicator light is 2 times greater than the conventional model (SMC comparison).


Auto Switch Internal Circuit


## D-M9PW(V)



D-M9BW(V)


Indicator light / Display method


Auto Switch Specifications

| PLC: Programmable Logic Controller |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| D-M9 $\square$ W/D-M9 $\square$ WV (With indicator light) |  |  |  |  |  |  |
| Auto switch part no. | D-M9NW | D-M9NWV | D-M9PW | D-M9PWV | D-M9BW | D-M9BWV |
| Electrical entry direction | In-line | Perpendicular | In-line | Perpendicular | In-line | Perpendicular |
| Wiring type | 3-wire |  |  |  | 2-wire |  |
| Output type | NPN |  | PNP |  |  | - |
| Applicable load | IC circuit, Relay, PLC |  |  |  | 24 VDC rer | relay, PLC |
| Power supply voltage | 5, 12, 24 VDC ( 4.5 to 28 V ) |  |  |  |  |  |
| Current consumption | 10 mA or less |  |  |  |  | - |
| Load voltage | 28 VDC | or less |  | - | 24 VDC (10 | to $28 \mathrm{VDC)}$ |
| Load current | 40 mA or less |  |  |  | 2.5 to | 40 mA |
| Internal voltage drop | 0.8 V or less at 10 mA ( 2 V or less at 40 mA ) |  |  |  | 4 V or | or less |
| Leakage current | $100 \mu \mathrm{~A}$ or less at 24 VDC |  |  |  | 0.8 mA | or less |
| Indicator light | Operating position $\rightarrow$ Red LED illuminates. Optimum operating position $\rightarrow$ Green LED illuminates. |  |  |  |  |  |
| Standard | Conforming to CE Standard |  |  |  |  |  |

- Lead wires $\rightarrow$ Oilproof heavy-duty vinyl cable: ø $2.7 \times 3.2$ ellipse

D-M9BW(V)
$0.15 \mathrm{~mm}^{2} \times 2$ cores
D-M9NW(V), D-M9PW(V) $0.15 \mathrm{~mm}^{2} \times 3$ cores
Note 1) Refer to page 22 for solid state switch common specifications.
Note 2) Refer to page 22 for lead wire lengths.
Weight Unit: g

| Auto switch part no. |  | D-M9NW(V) | D-M9PW(V) | D-M9BW(V) |
| :---: | :---: | :---: | :---: | :---: |
| Lead wire length <br> $(m)$ | 0.5 | 8 | 8 | 7 |
|  | 1 | 14 | 14 | 13 |
|  | 3 | 41 | 41 | 38 |
|  | 5 | 68 | 68 | 63 |

## Dimensions

Unit: mm

2.7

D-M9 $\square$ WV


# Water Resistant 2-Colour Indication Solid State Switch: Direct Mounting Style D-M9NA(V)/D-M9PA(V)/D-M9BA(V) C E 

## Grommet

- Water (coolant) resistant type
- 2-wire load current is reduced ( 2.5 to 40 mA ).
- UL certified (style 2844) lead cable is used.
- The optimum operating position can be determined by the colour of the light. (Red $\rightarrow$ Green $\leftarrow$ Red)


Auto Switch Internal Circuit
D-M9NA(V)


D-M9PA(V)


D-M9BA(V)


Indicator light / Display method


## Auto Switch Specifications

| PLC: Programmable Logic Controller |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| D-M9 $\square$ A/D-M9 $\square$ AV (With indicator light) |  |  |  |  |  |  |
| Auto switch part no. | D-M9NA | D-M9NAV | D-M9PA | D-M9PAV | D-M9BA | D-M9BAV |
| Electrical entry direction | In-line | Perpendicular | In-line | Perpendicular | In-line | Perpendicular |
| Wiring type | 3-wire |  |  |  | 2-wire |  |
| Output type | NPN |  | PNP |  | - |  |
| Applicable load | IC circuit, Relay, PLC |  |  |  | 24 VDC relay, PLC |  |
| Power supply voltage | 5, 12, 24 VDC ( 4.5 to 28 V ) |  |  |  | - |  |
| Current consumption | 10 mA or less |  |  |  | - |  |
| Load voltage | 28 VDC | or less |  | - | 24 VDC (10 | to $28 \mathrm{VDC)}$ |
| Load current | 40 mA or less |  |  |  | 2.5 to 40 mA |  |
| Internal voltage drop | 0.8 V or less at 10 mA ( 2 V or less at 40 mA ) |  |  |  | 4 V or less |  |
| Leakage current | $100 \mu \mathrm{~A}$ or less at 24 VDC |  |  |  | 0.8 mA or less |  |
| Indicator light | Operating position $\rightarrow$ Red LED illuminates. <br> Optimum operating position $\rightarrow$ Green LED illuminates. |  |  |  |  |  |
| Standard | Conforming to CE Standard |  |  |  |  |  |

$\bullet$ Lead wires $\rightarrow$ Oilproof heavy-duty vinyl cable: $\varnothing 2.7 \times 3.2$ ellipse D-M9BA(V)
$0.15 \mathrm{~mm}^{2} \times 2$ cores
D-M9NA(V), D-M9PA(V) $\quad 0.15 \mathrm{~mm}^{2} \times 3$ cores
Note 1) Refer to page 22 for solid state switch common specifications.
Note 2) Refer to page 22 for lead wire lengths.
Weight Unit: g

| Auto switch part no. |  | D-M9NA(V) | D-M9PA(V) | D-M9BA(V) |
| :---: | :---: | :---: | :---: | :---: |
| Lead wire length <br> $(m)$ | 0.5 | 8 | 8 | 7 |
|  | 1 | 14 | 14 | 13 |
|  | 3 | 41 | 41 | 38 |
|  | 5 | 68 | 68 | 63 |

Dimensions
Unit: mm


D-M9 $\square$ AV


Mounting screw M2.5 $\times 4 e$ Slotted set screw (flat end) Indicator light


## Series MSQX

Made to Order

Please contact SMC for detailed specifications, lead times and prices.

## With External Stopper

Symbol

Prevent holding torque from being halved at the rotation end.

## How to Order



## Specifications

| Size | 10 | 20 | $\mathbf{3 0}$ | 50 |
| :--- | :---: | :---: | :---: | :---: |
| Rotation angle | $90^{\circ}, 180^{\circ}$ |  |  |  |
| Angle adjustment range | Each rotation end ${ }_{-5^{\circ}}{ }^{\circ}$ |  |  |  |

Note) Specifications other than the above are the same as standard.

## Weight

| Size | $\mathbf{1 0}$ | $\mathbf{2 0}$ | $\mathbf{3 0}$ | $\mathbf{5 0}$ |
| :---: | :---: | :---: | :---: | :---: |
| $90^{\circ}$ spec. | 630 | 1200 | 1520 | 2480 |
| $180^{\circ}$ spec. | 600 | 1140 | 1450 | 2370 |

Note) Values excluding the weight of the auto switches.
(g)
o

## Dimensions



X150/X151/X152/X153

Series CRQ2X/MSQX Safety Instructions

These safety instructions are intended to prevent a hazardous situation and/or equipment damage. These instructions indicate the level of potential hazard by labels of "Caution", "Warning" or "Danger". To ensure safety, be sure to observe ISO 4414 Note 1), JIS B 8370 Note 2) and other safety practices.

Explanation of the Labels

| Labels | Explanation of the labels |
| :---: | :---: |
| \ D Danger | In extreme conditions, there is a possible result of serious injury or loss of life. |
| ¢ Warning | Operator error could result in serious injury or loss of life. |
| \ Caution | Operator error could result in injury ${ }^{\text {Note }}$ 3) or equipment damage. ${ }^{\text {Note 4) }}$ |

Note 1) ISO 4414: Pneumatic fluid power - General rules relating to systems
Note 2) JIS B 8370: General Rules for Pneumatic Equipment
Note 3) Injury indicates light wounds, burns and electrical shocks that do not require hospitalization or hospital visits for long-term medical treatment.
Note 4) Equipment damage refers to extensive damage to the equipment and surrounding devices.

## Selection/Handling/Applications

1. The compatibility of the pneumatic equipment is the responsibility of the person who designs the pneumatic system or decides its specifications.
Since the products specified here are used in various operating conditions, their compatibility for the specific pneumatic system must be based on specifications or post analysis and/or tests to meet the specific requirements. The expected performance and safety assurance are responsibility of the person who has determined the compatibility of the system. This person should continuously review the suitability of all items specified, referring to the latest catalogue information with a view to giving due consideration to any possibility of equipment failure when configuring a system.
2. Only trained personnel should operate pneumatically operated machinery and equipment.

Compressed air can be dangerous if handled incorrectly. Assembly, handling or repair of pneumatic systems should be performed by trained and experienced operators. (Understanding JIS B 8370 General Rules for Pneumatic Equipment, and other safety rules are included.)
3. Do not service machinery/equipment or attempt to remove components until safety is confirmed.

1. Inspection and maintenance of machinery/equipment should only be performed after confirmation of safe locked-out control positions.
2. When equipment is to be removed, confirm that safety process as mentioned above. Cut the supply pressure for this equipment and exhaust all residual compressed air in the system.
3. Before machinery/equipment is restarted, take measures to prevent shooting-out of cylinder piston rod, etc. (Bleed air into the system gradually to create back pressure).
4. Contact SMC if the product is to be used in any of the following conditions:
5. Conditions and environments beyond the given specifications, or if product is used outdoors.
6. Installation on equipment in conjunction with atomic energy, railway, air navigation, vehicles, medical equipment, food and beverages, recreation equipment, emergency stop circuits, press applications, or safety equipment.
7. An application which has the possibility of having negative effects on people, property, requiring special safety analysis.
8. If the products are used in an interlock circuit, prepare a double interlock style circuit with a mechanical protection function for the prevention of a breakdown. And, examine the devices periodically if they function normally or not.

## Exemption from Liability

1. SMC, its officers and employees shall be exempted from liability for any loss or damage arising out of earthquakes or fire, action by a third person, accidents, customer error with or without intention, product misuse, and any other damages caused by abnormal operating conditions.
2. SMC, its officers and employees shall be exempted from liability for any direct or indirect loss or damage, including consequential loss or damage, loss of profits, or loss of chance, claims, demands, proceedings, costs, expenses, awards, judgments and any other liability whatsoever including legal costs and expenses, which may be suffered or incurred, whether in tort (including negligence), contract, breach of statutory duty, equity or otherwise.
3. SMC is exempted from liability for any damages caused by operations not contained in the catalogues and/or instruction manuals, and operations outside of the specification range.
4. SMC is exempted from liability for any loss or damage whatsoever caused by malfunctions of its products when combined with other devices or software.

# Series CRQ2X/MSQX Auto Switches Precautions 1 

$\triangle$

## Be sure to read this before handling.

## Design and Selection

## $\triangle$ Warning

## 1. Confirm the specifications.

Read the specifications carefully and use this product appropriately.
The product may be damaged or malfunction if it is used outside the range of specifications of current load, voltage, temperature or impact.
2. Pay attention to the length of time that a switch is ON at an intermediate stroke position.
When an auto switch is placed at an intermediate position of the stroke and a load is driven at the time the piston passes, the auto switch will operate. However if the speed is too great, the operating time will be shortened and the load may not operate properly. The maximum detectable piston speed is:

$$
\mathrm{V}(\mathrm{~mm} / \mathrm{s})=\frac{\text { Auto switch operating range }(\mathrm{mm})}{\text { Load operating time }(\mathrm{ms})} \times 1000
$$

3. Keep wiring as short as possible.

## <Reed switch>

As the length of the wiring to a load gets longer, the rush current at switching ON becomes greater, and this may shorten the product's life. (The switch will stay ON all the time).
Use a contact protection box when the wire length is 5 m or longer.

## <Solid state switch>

Although wire length should not affect switch function, use a wire 100 m or shorter.
If the wiring is longer it will likely increase noise (although the length is less than 100 m ). In these cases, SMC recommends attaching the ferrite core to the both ends of the cable to prevent excess noise.
Since the solid state auto switch is a semiconductor switch which has no contacts, no protection box is needed.
4. Do not use a load that generates surge voltage.
<Reed switch>
If driving a load such as a relay that generates a surge voltage, use a switch with a built-in contact protection circuit or use a contact protection box.

## <Solid state switch>

Although a zener diode for surge protection is connected at the output side of a solid state auto switch, damage may still occur if the surge is applied repeatedly. When a load, such as a relay or solenoid, which generates surge is directly driven, use a type of switch with a built-in surge absorbing element.

## 5. Cautions for use in an interlock circuit

When an auto switch is used for an interlock signal requiring high reliability, devise a double interlock system to avoid trouble by providing a mechanical protection function, or by also using another switch (sensor) together with the auto switch. Also perform periodic maintenance and confirm proper operation.
6. Do not make any modifications (including exchanging the printed circuit boards) to the product. It may cause human injuries and accidents.

## $\triangle$ Caution

1. Take precautions when actuators are used close together.
When multiple auto switch actuators are used in close proximity magnetic field interference may cause the switches to malfunction. Maintain a minimum actuator separation of 40 mm . (When the allowable separation is indicated for each actuator series, use the specified value.)
Use of a magnetic screen plate (MU-S025) or magnetic screen tape can reduce the interference of magnetic force.
2. Take note of the internal voltage drop of the auto switch.

## <Reed switch>

1) Auto switches with an indicator light (Model D-A96(V))

- If auto switches are connected in series as shown below, take note that there will be a large voltage drop because of internal resistance in the light emitting diodes. (Refer to internal voltage drop in the auto switch specifications.)
[The voltage drop will be " $n$ " times larger when " $n$ " auto switches are connected.]
Even though an auto switch operates normally, the load may not operate.

- In the same way, when operating under a specified voltage, although an auto switch may operate normally, the load may not operate. Therefore, the formula below should be satisfied after confirming the minimum operating voltage of the load.

| Supply |
| :---: |
| voltage | | Internal voltage |
| :---: |
| drop of switch |$>$| Minimum operating |
| :---: |
| voltage of load |

2) If the internal resistance of a light emitting diode causes a problem, select a switch without an indicator light (Model DA90).

## <Solid state switch>

3) Generally, the internal voltage drop will be greater with a 2wire solid state auto switch than with a reed switch. Take the same precautions as in 1).
Also, note that a 12 VDC relay is not applicable.

Series CRQ2X/MSQX Auto Switches Precautions 2

Be sure to read this before handling.

## Design and Selection

## $\triangle$ Caution

## 3. Pay attention to leakage current.

## <Solid state switch>

With a 2 -wire solid state auto switch, current (leakage current) flows to the load to operate the internal circuit even when in the OFF state

$$
\begin{aligned}
& \text { Operating current of } \\
& \text { load (OFF condition) }
\end{aligned}
$$

If the criteria given in the above formula are not met, it will not reset correctly (stays ON). Use a 3 -wire switch if this specification will not be satisfied.
Moreover, leakage current flow to the load will be " $n$ " times larger when " n " auto switches are connected in parallel.
4. Ensure sufficient space for maintenance activities.

When designing an application, be sure to allow sufficient space for maintenance and inspections.
5. Minimum stroke for auto switch mounting.

The minimum stroke value for mounting one or two auto switches is obtained once the switch detects the cylinder stroke ends.
However, even if the switch is mounted at the proper position within the minimum stroke range, it may not be able to detect when the piston stops in the middle of the stroke due to a stopper, etc. It may also turn on in the middle of a stroke.
6. When multiple auto switches are required.
" $n$ " indicates the number of switches that can be physically mounted. Detection intervals depend on the switch mounting structure and set position therefore some required interval and set positions may not be available.
7. Limitations of detectable positioning.

When using certain mounting brackets, the surface and position where an auto switch can be mounted could be restricted due to physical interference (bottom side of foot bracket etc.).
Please select the set position of the auto switch so that it does not interfere with the mounting bracket of the cylinder (trunnion or support ring etc.).
8. Use the cylinder and switch in proper combination.

The auto switch is pre-adjusted to activate properly for an auto-switch-capable SMC cylinder.
If the auto switch is mounted improperly, or used for another cylinder series, the switch may not activate properly.

## Mounting and Adjustment

## © Warning

## 1. Operating manual

Install the products and operate them only after reading the operating manual carefully and understanding its contents. Also keep the manual where it can be referred to if necessary.
2. Do not drop or bump.

Do not drop, bump or apply excessive impacts ( $300 \mathrm{~m} / \mathrm{s}^{2}$ or more for reed switches and $1000 \mathrm{~m} / \mathrm{s}^{2}$ or more for solid state switches) while handling. Although the body of the auto switch may not be damaged, the inside of the auto switch could be damaged and cause a malfunction.
3. Mount auto switches using the proper fastening torque.
When a switch is tightened beyond the range of fastening torque, the mounting screws, auto switches, and mounting bracket, may be damaged. On the other hand, tightening below the range of fastening torque may allow the switch to slip out of position. (Refer to auto switch mounting for each series regarding auto switch mounting, moving, and fastening torque, etc.)
4. Mount an auto switch at the center of the operating range.
Adjust the mounting position of an auto switch so that the piston stops at the center of the operating range (the range in which a switch is ON). (The mounting positions shown in a catalogue indicate the optimum positions at stroke end.) If mounted at the end of the operating range (around the borderline of ON and OFF), operation may be unstable.
<D-M9■>
When the auto switch is used to replace an old series auto switch, it may not activate depending on operating condition because of its shorter operating range.
Such as:

- Application where the stop position of actuator may vary and exceed the operating range of the auto switch, for example, pushing, pressing, clamping operation, etc.
- Application where the auto switch is used for detecting an intermediate stop position of the actuator. (In this case the detecting time will be reduced. )
In these applications, set the auto switch to the center of the required detecting range.


## 5. Secure the space for maintenance.

When installing the products, please consider access for maintenance.

## $\triangle$ Caution

1. Do not carry an actuator by the auto switch lead wires.
Never carry a rotary actuator by its lead wires, as this may not only cause broken lead wires, but it may cause internal elements of the auto switch to be damaged by the stress.
2. Fix the auto switch with appropriate screw installed on the auto switch body. If using other screws, auto switch may be damaged.

# Series CRQ2X/MSQX Auto Switches <br> Precautions 3 

$\triangle$

## Be sure to read this before handling.

## Wiring

## . Warning

## 1. Confirm proper insulation of wiring.

Be sure there is no faulty wiring insulation (contact with other circuits, ground fault, improper insulation between terminals, etc.). Damage may occur due to excess current flow into a switch.
2. Do not wire with power lines or high-voltage lines.

Wire separately from power lines or high-voltage lines, avoiding parallel wiring or wiring in the same conduit with these lines. Control circuits, including auto switches, may malfunction due to noise from those other lines.

## $\triangle$ Caution

1. Avoid repeatedly bending or stretching lead wires.

Broken lead wires will result from applying bending stress or stretching force to the lead wires.
2. Be sure to connect the load before power is applied. <2-wire type>
If the power is turned ON when an auto switch is not connected to a load, the switch will be instantly damaged because of excess current.
3. Do not allow short circuit of loads.

## <Reed switch>

If the power is turned ON with a load in a short circuited condition, the switch will be instantly damaged because of excess current flow into the switch.

## <Solid state switch>

Model D-M9 $\square(\mathrm{V})$ except $\mathrm{D}-\mathrm{M} 9 \square \mathrm{~W}(\mathrm{~V})$ and all models of PNP output type switches do not have built-in short circuit protection circuits. As in the case of reed switches, if loads are short circuited, the switches will be instantly damaged.
Take special care to avoid reverse wiring with the brown power supply line and the black output line on 3 -wire type switches.

## . Caution

## 4. Avoid incorrect wiring.

## <Reed switch>

A 24 VDC switch with indicator light has polarity. The brown lead wire is (+) and the blue lead wire, or the second terminal, is $(-)$.

1) If connections are reversed, a switch will operate, however, the light emitting diode will not light up.
Also note that a current greater than that specified will damage a light emitting diode and it will no longer operate.
Applicable models: D-A93, D-A54

## <Solid state switch>

1) If connections are reversed on a 2 -wire type switch, the auto switch will not be damaged if protected by a protection circuit, but the switch will stay in an ON state.
However, it is still necessary to avoid reversed connections, since the auto switch could be damaged by a load short circuit in this condition.
2) If connections are reversed (power supply line + and power supply line -) on a 3 -wire type switch, the switch will be protected by a protection circuit. However, if the power supply line (+) is connected to the blue wire and the power supply line (-) is connected to the black wire, the auto switch will be damaged.
<D-M9■>
The D-M9 $\square$ does not have built-in short circuit protection circuit. Be aware that if the power supply connection is reversed (e.g. (+) power supply wire and (-) power supply wire connection is reversed), the auto switch will be damaged.
5. When the cable sheath is stripped, confirm the stripping direction. The insulator may be split or damaged depending on the direction. (D-M9 only)


Recommended Tool

| Model name | Model no. |
| :---: | :---: |
| Wire stripper | D-M9N-SWY |

[^4]

Series CRQ2X/MSQX Auto Switches Precautions 4
Be sure to read this before handling.

## . Warning

1. Never use in an atmosphere of explosive gases.

The construction of auto switches is not intended to prevent explosion. Never use in an atmosphere with an explosive gas since this may cause a serious explosion.
2. Do not use in an area where a magnetic field is generated.
Auto switches will malfunction or magnets inside actuators will become demagnetized. (Consult SMC regarding the availability of a magnetic field resistant auto switch).
3. Do not use in an environment where the auto switch will be continually exposed to water.
Although switches, except some models, satisfy IEC standard IP67 construction (JIS C 0920: waterproof construction), do not use switches in applications where continually exposed to water splash or spray. Poor insulation or swelling of the potting resin inside auto switches may cause malfunction.
4. Do not use in an environment with oil or chemicals.

Consult with SMC if auto switches will be used in an environment with coolant, cleaning solvent, various oils or chemicals. If auto switches are used under these conditions for even a short time, they may be adversely affected by improper insulation, malfunction due to swelling of the potting resin, or hardening of the lead wires.
5. Do not use in an environment with temperature cycles.
Consult with SMC if switches are used where there are temperature cycles other than normal temperature changes, as they may be adversely affected internally.
6. Do not use in an environment where there is excessive impact shock.
<Reed switch>
When excessive impact ( $300 \mathrm{~m} / \mathrm{s}^{2}$ or more) is applied to a reed switch during operation, the contact point will malfunction and generate or cut off a signal momentarily ( 1 ms or less). Consult SMC regarding the need to use a solid state switch depending upon the environment.
7. Do not use in an area where surges are generated. <Solid state switch>
When there are units (solenoid type lifter, high-frequency induction furnace, motor, radio equipment etc.) which generate a large amount of surges or electromagnetic waves in the area around actuators with solid state auto switches, this may cause deterioration or damage to the internal circuits elements of the switches. Avoid sources of surge generation and disorganized lines.

## $\triangle$ Caution

1. Avoid accumulation of iron debris or close contact with magnetic substances.
When a large amount of ferrous debris such as machining chips or spatter, is accumulated, or a magnetic substance is brought into close proximity with an auto switch actuator, it may cause the auto switch (actuator) to malfunction due to a loss of the magnetic force inside the actuator.
2. Consult SMC concerning water resistance, elasticity of lead wires, use at welding sites, etc.
3. Do not use in environments with direct sunlight.
4. Do not mount the product in locations exposed to radiant heat.

## Maintenance

## $\triangle$ Warning

1. Perform the following maintenance periodically in order to prevent possible danger due to unexpected auto switch malfunction.
1) Secure and tighten auto switch mounting screws. If screws become loose or the mounting position is dislocated, retighten them after readjusting the mounting position.
2) Confirm that there is no damage to lead wires.

To prevent faulty insulation, replace auto switches or repair lead wires, etc., if damage is discovered.
3) Confirm the lighting of the green light on the 2-colour indicator type auto switch.
Confirm that the green LED is on when stopped at the established position. If the red LED is on, the mounting position is not appropriate. Readjust the mounting position until the green LED lights up.
2. Maintenance procedures are outlined in the operation manual.
Not following proper procedures could cause the product to malfunction and could lead to damage to the equipment or machine.
3. Removal of equipment, and supply/exhaust of compressed air.
Before any machinery or equipment is removed, first ensure that the appropriate measures are in place to prevent the fall or erratic movement of driven objects and equipment. Then cut off the electric power and reduce the pressure in the system to zero. Only then you should proceed with the removal of any machinery and/or equipment.
When machinery is restarted, proceed with caution after confirming that appropriate measures are in place to prevent actuators from sudden movement.

Series CRQ2X/MSQX Specific Product Precautions
Be sure to read this before handling.

## Selection

## $\triangle$ Caution

1. Changes in speed occur in applications where there are changes in the load during operation, such as the load being lifted (lowered) against gravity.
2. The purpose of this product is to provide stable rotation at low-speed.
It does not provide any function to cushion the impact at the operation start or end.
3. Speed may vary at the rotation end depending on operating conditions. (This phenomenon can be avoided by using an external stopper.)

## Air Supply

## $\triangle$ Caution

1. Do not use at dew point of $-60^{\circ} \mathrm{C}$ or lower.

Operation at dew point of $-60^{\circ} \mathrm{C}$ or lower may adversely affect the lubricant used inside the switch and can lead to operation failure. EUROPEAN SUBSIDIARIES:


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[^0]:    Note) If the rotation time exceeds 2 s per $90^{\circ}$, kinetic energy is calculated with rotation time of 2 s per $90^{\circ}$.

[^1]:    Note) Valve excluding the weight of auto switches

[^2]:    Made to Order $\rightarrow$ Refer to "SMC Best Pneumatics 2004" Vol. 11 catalogue.

[^3]:    Note) Value excluding the weight of the auto switches.

[^4]:    * Stripper for a round cable (ø2.0) can be used for a 2-wire type cable.

